

Schématisme :  
logique des jugements  
VS  
géométrie des phénomènes

Jean Petitot (CAMS-EHESS)

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Séminaire A. Callu, F. Forestier et P. Lochak, ENS

- Fil directeur : *le schématisme*.
  - Un pôle logico-linguistique (logique des jugements au sens traditionnel de prédication),
  - Un pôle de *format* d'objet (souvent intuitif, géométrique, morphologique).
- Lien entre les deux.

- Relier une logique à une structure objectale et à des modèles d'objets (ce que Husserl appelait une “ontologie régionale”) est un problème “transcendantal”.

- Physique mathématique.
- Phénoménologie de la perception.
- Structuralisme : phonologie, linguistique cognitive, sémiotique (Thèse: *Pour un schématisme de la structure*).
- Esthétique.

- Deux problématiques :
  - physique au niveau fondationnel le plus élémentaire,
  - phénoménologie de la perception.
- “Logique” est pris au sens le plus élémentaire et classique (aristotélicien) de “prédication” : attribution de propriétés à des entités sans tenir compte de la façon dont les entités sont *constituées* en objets d'une science particulière.

# Physique

- L'exemple de la phoronomie (cinématique) chez Kant dans les *Metaphysische Anfangsgründe der Naturwissenschaft* (1786).
- Cf. Jules Vuillemin : *Physique et métaphysique kantiennes* (1955).
- Michael Friedman : *Kant's Construction of Nature* (2013).

- Logique générale “pure” analytique et formelle.
- Elle ne concerne que la “forme de la pensée” et fait abstraction de la spécificité des domaines de connaissance.
- C'est un “canon” de l'entendement et pas un “organon”.
- C'est une simple “logique de la vérité” (le vrai/faux des jugements).
- La logique générale “appliquée” tient compte de la psychologie associée.

- Une logique contrainte par les structures synthétiques a priori d'un domaine d'objet (“ontologie régionale” chez Husserl) est une logique *transcendantale*.
- Elle seule peut être un “organon” pour la science considérée.



- Les MAN traitent de l'exemple de la mécanique newtonienne.
- L'objet régional est le *mouvement* (Bewegung).
- Les catégories *ne sont pas* directement applicables, en tant que “concepts purs de l'entendement”, à un objet régional spécifique.
- Elles nécessitent un *schématisme* les transformant en *méthodes de construction d'objets*.

- **Remarque.** C'est évident pour les concepts *empiriques* : transformer le *concept* de chat en des méthodes de construction *d'images* de chats. Mais c'est un énorme problème neurocognitif (“art caché dans les profondeurs de l'âme” disait Kant).
- Ici, le schème *transcendantal* de la quantité est le nombre et, pour une ontologie régionale donnée, concerne ce qui permet de *calculer* sur les phénomènes de la région avec des *algèbres* de nombres.

- Pourquoi Kant a-t-il dû introduire un nouveau type de jugements à cause de la relativité galiléenne ?
- C'est aujourd'hui totalement trivial, mais à l'époque cela ne l'était pas du tout.
- C'est la première mise en crise de la logique élémentaire des jugements par un problème fondationnel (“Anfangsgründe”) venant de la physique (révolution galileo-newtonienne).
- Pour Kant : objectivité physique (“factum rationis”) > logique.

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# Phoronomy

- *Phenomenality* of motion is characterized by transformations of frames.
- Phoronomy concerns the motion of matter (Bewegung) relative to an inertial frame (relative Raum).
- Inertial frames are governed by Galilean relativity.

**Kinematics**

Background structure: space and time.  
Observable states: position and velocity.  
Measuring: Euclidean metric and arithmetic.  
Algebraic structure: composing motions.  
Galilean relativity and inertial frames.

**Phoronomy**

Categories of quantity.  
Extensive magnitudes.  
Axioms of intuition.

**Dynamics**

Primitive internal forces inside matter  
(repulsion, attraction).  
Reduction of matter to mass.

**Dynamics**

Categories of quality.  
Intensive magnitudes.  
Anticipations of perception.

**Mechanics**

Conservation laws. Invariance.  
Newton law: Galilean invariance.  
Action-reaction equality

**Mechanics**

Categories of relation.  
Analogies of experience: permanence of  
substance, causality, coexistence.

**Phenomenology**

Categories of modality.  
Postulates of empirical thought in general.

- The fundamental problem of *Phoronomy* : inertial motions as “magnitudes” (Grösse) must be *algebraically* constructed as “quantities” (quantitas).
- *Axioms of Intuition* : a magnitude is “composition of the homogeneous” (*Zusammensetzung des Gleichartigen*, B202).
- There must exist *mathematical operations of composition* for magnitudes (an algebra).

- The *algebraic* composition (*Zusammensetzung*) of velocities of inertial motions must be deduced from the *phenomenal* composition of changes of frame and from their Galilean relativity.
- Key problem : relativity implies that the algebraic composition *is not physical* and cannot be a composition *inherent* to matter (as it is the case for accelerations).

- For Newton, there exists an *absolute space* and therefore Galilean relativity is not metaphysically disruptive.
- For Kant, absolute space is antinomic and cannot be introduced in physics.
  - “Absolute space is (...) in itself nothing, and no object at all.” (481/16).
  - “An absolute motion (...) cannot be experienced at all” (487/23).
  - “Absolute space is nothing for all possible experience” (488/23).



- Absolute space is only “an Idea of Reason”.
- It is the same for an absolute position in space, an absolute direction in space, an absolute moment in time.
- Physics had to wait until its Lagrangian formulation to correlate these relativities to fundamental conservation laws via Noether's theorem : momentum, angular momentum, energy, center of mass.

- Nevertheless, Kant admits that if, far beyond Phoronomy, we look at all the gravitational inter-actions between all bodies in the universe, we can choose a special *cosmological* inertial frame attached to the *center of mass* of the universe and acting as a surrogate of the absolute space. But this has no sense at the phoronomical level.

- The consequence of this radical conception of Galilean relativity, is that *velocities cannot be attached to bodies* and added as vectors attached to a single and same body (the parallelogram rule).
- Accelerations can be attached to bodies because they are Galilean invariants, but not velocities.

- Lehrsatz :

“The composition of two motions of one and the same point can only be thought in such a way that one of them is represented in absolute space, and, instead of the other, a motion of the relative space with the same speed occurring in the opposite direction is represented as the same as the latter.” (490/26).

- The problem is that  $v_K$  is a relative  $v_{K/F}$  and the composition  $+$  for the  $v$  must respect the composition of the  $K/F$ .
- But  $K/F$  and  $(K/F)'$  cannot be composed (obstruction). Only  $K/F$  and  $F/F'$  can be composed (this gives  $K/F'$ ), or  $F'/K$  and  $K/F$  (this gives  $F'/F$ ).

- “Axiom” : if  $K$  is a body with linear uniform (LU) motion of velocity  $v$ , to add  $w$  to  $v$  means
  - to look at the inertial frame  $F_0$  where  $K$  has velocity  $v$ ,
  - to take the inertial frame  $F_1$  with velocity  $-w$  w.r.t.  $F_0$ ,
  - and to take the velocity of  $K$  w.r.t.  $F_1$ .
- Kant was very proud of this axiom concerning the "observer" ("Zuschauer") side and the background structure.

- The equality of motions is called “Kongruenz”.

“[The] congruence of two combined motions with a third (as with the *motus compositus* itself) can never take place if this two combined motions are represented in one and the same space.” (493/29, Remark 1 of the Proposition).

- The phoronomic “*construction*” of motion is this *conversion* of relativity into an algebraic calculus (vector space).

- A magnitude (*Grösse*) becomes a *quantitas* (vector with module, *Geschwindigkeit*, and direction *Richtung*):

$$\left\{ \begin{array}{l} v + w : (\mathbb{R}^+, +), \text{ same line, same direction} \\ v + w : (\mathbb{R}, +), \text{ same line} \\ v + w : (\mathbb{R}^2, +), \text{ parallelogram rule} \end{array} \right.$$

- LU motions of inertial frames :  
composition  $*$  (as in categories)

$$(F_2/F_0) * (F_0/F_1) = (F_2/F_1)$$

$$(F_0/F_1) * (F_1/F_0) = Id_{F_0}$$

- Velocity vectors : algebraic operation  $+$
- Relation between the two :

$$v_{F_2/F_0} + v_{F_0/F_1} = v_{(F_2/F_0)*(F_0/F_1)}$$



- So, moving bodies  $K$  have “kinematical states”  $\rho = K/L$  but the result of a measure of  $v$  in a state does not measure a true property of  $K$ .

- In fact the problem is quite subtle because Kant works in the tangent spaces  $T_x E$  of the space  $E$  at  $x$ .
- He considers the LU motions “tangent” to motions.

# Relativity and judgment

- With Phoronomy and relativity, Kant ran into a deep philosophical problem.
- He tackled it in the *Phenomenology*, which develops the categories of modality and the Postulates of the empirical thought in general.
- How a logic of judgments can be compatible with the object format "background structure + Galilean relativity" ?

- Due to relativity, a judgment such as  
“the body  $K$  has velocity  $v_K$ ”  
has *no* physical content, *no* ascribable truth value.
- "In Phoronomy (...) it is completely undetermined and arbitrary how much speed, if any, I wish to ascribe to the one [the body] or to the other [the frame]."

- Phronomy concerns motions as phenomena and not objects of experience.
- But logic concerns the relation of knowledge to *objects* :

*disjunctive* judgments, predicates, and *truth values*.

“of two *objectively* opposed predicates, one is assumed to the exclusion of the other for the determination of the object.” (556/95).

- Law of the excluded middle.

- But Phoronomy as *Erscheinungslehre* concerns the relation of knowledge to *the subject* (Zuschauer, observer) :  
alternative judgments and relativity.

“of two judgments objectively equivalent, yet subjectively opposed to one another, one is assumed for the determination of the object without excluding its opposite – and thus by mere choice.” (Ibidem)

“For here the proposition that the body is either moved and the space at rest, or conversely, is not a disjunctive proposition in an objective relation, but only in a subjective one, and the two judgments contained therein are valid alternatively.” (560/99).

- The difference “phenomenon VS object” is expressed on the side of judgments by the difference between
  - disjunctive judgments,
  - alternative judgments.
- Disjunctive judgments can have truth values, that is  $v_K = v$  or  $v_K \neq v$  is true.
- Alternative judgments cannot have truth values : since two predicates objectively contradictory can be ascribed:  $v_K = v$  and  $v_K \neq v$  can be true at the same time.

- Kant says that they are only “possible” judgments ascribing a predicate.
- There is a problem of “*value definiteness*”: “to have a value” does not mean “to possess a property”.
- Relativity means that the concept of velocity is contextual, relative to an observer (*Zuschauer*).
- Only the  $(K, F, v_{K/F})$  have a physical content.



- For inertial motions there exists no “element of physical reality” associated to velocity (no physical content).
- Ontological realism is excluded by the theory itself.

- This problem had deep consequences after Kant for EM.
- The motion of a charged particule in an EM field is driven by the force

$$F = q(E + v \wedge B) .$$

- But  $F$  is Gal-invariant while  $v$  is not.
- Therefore the formula seems to be not well composed. It is a problem.
- Solution : the decomposition  $(E, B)$  of the EM field depends on the inertiel frame.  $E$  and  $B$  do not exist as independent fields.

- $E$  is generated by static charges and  $B$  by moving charges and, in another inertial frame with velocity  $V$ ,  $E$  becomes  $E + V \wedge B$  and  $B$  remains  $B$ .
- Furthermore, the group of relativity for the Maxwell equations of the EM field  $(E, B)$  is not the Galilean group but the Lorentz group.

- Physicists introduced the “aether” converting the empty space into a *physical* (paradoxical) substrate w.r.t. which  $v$  becomes “absolute”.
- They needed to introduce contractions of length and dilations of time.

- But the addition of velocities remained paradoxical ( $c$  is constant, Michelson-Morley).
- Einstein “dephysicalized” the aether, turned back to a pure kinematics with a new relativity group (Lorentz).
- But a sort of aether regained a physical status with the quantum vacuum.

# Quantum mechanics

- Philosophy of quantum mechanics faced the same type of problem, but in a much more acute way.
- Quantum Logic.
- Bohr topos (Chris Isham, Jeremy Butterfield, Andreas Döring, Chris Heunen, Bas Spitters, etc.) .

- In QM the obstruction to ascribe truth values to judgments comes from the non-commutativity of the algebra of observables.

- The problem is well known since Bell and Kochen-Specker no-go theorems.
- Value definiteness and non contextuality.  
 K-S : For  $\dim(\mathcal{H}) \geq 3$  ( $\mathcal{H}$  the Hilbert space of the system) it is impossible to ascribe definite values  $V(a)$  to the observables  $a$  with the hypotheses :
  - the *measure* of  $a$  gives  $V(a) \Leftrightarrow$  the system *has* an *intrinsic property* (non contextual) whose value is  $V(a)$ ,
  - *FUNC* :  $V(f(a, b)) = f(V(a), V(b))$



- No-go theorems show that “measure” is not “predication”.
- There exists a gap between:
  - “the measure of the observable  $a$  gives the result  $r$  when the system is in state  $\rho$ ”, and
  - “when the system is in state  $\rho$ , the quantity  $a$  has the value  $r$  .”
- There exists no “element of physical reality” associated to a measure.

- Simon Kochen-Ernst Specker (1967) :
- They worked out an exemple with  $\dim(\mathfrak{H}) = 3$  and 117 observables.
- Adán Cabello (1996) worked out a simpler example with  $\dim(\mathfrak{H}) = 4$  and 18 observables.
- To each observable is associated an orthonormal frame of eigenvectors and 4 projectors  $P_i$  (yes-no questions) with

$$V(P_i) = 0 \text{ or } 1$$

$$\sum_i V(P_i) = 1$$

- In each frame one  $P$  has  $V(P) = 1$  and three  $P$  have  $V(P) = 0$ .

- Cabello found 9 orthonormal frames

$$9 \times 4 = 36$$

where each axis is counted 2 times

$$36 = 18 \times 2$$

- Non contextuality implies that the  $V(P)$  are *intrinsic* and do not depend upon the frame.

- When we add the 9  $\sum_i V(P_i) = 1$   
the RHS is 9 (odd) and the LHS is even  
since the  $V(P)$  are *intrinsic* and each appears  
two times.

$u_1$	(0, 0, 0, 1)	(0, 0, 0, 1)	(1, -1, 1, -1)	(1, -1, 1, -1)	(0, 0, 1, 0)	(1, -1, -1, 1)	(1, 1, -1, 1)	(1, 1, -1, 1)	(1, 1, 1, -1)
$u_2$	(0, 0, 1, 0)	(0, 1, 0, 0)	(1, -1, -1, 1)	(1, 1, 1, 1)	(0, 1, 0, 0)	(1, 1, 1, 1)	(1, 1, 1, -1)	(-1, 1, 1, 1)	(-1, 1, 1, 1)
$u_3$	(1, 1, 0, 0)	(1, 0, 1, 0)	(1, 1, 0, 0)	(1, 0, -1, 0)	(1, 0, 0, 1)	(1, 0, 0, -1)	(1, -1, 0, 0)	(1, 0, 1, 0)	(1, 0, 0, 1)
$u_4$	(1, -1, 0, 0)	(1, 0, -1, 0)	(0, 0, 1, 1)	(0, 1, 0, -1)	(1, 0, 0, -1)	(0, 1, -1, 0)	(0, 0, 1, 1)	(0, 1, 0, -1)	(0, 1, -1, 0)

# Transcendental logic and topos theory

- On the “judgment” side we find *logic*.
- On the “objective” side we find *geometrical* structures of objects (vector spaces, relativity groups, Hilbert spaces, C\*-algebras, etc.).

- To combine both sides, that is logic and geometry, is the transcendental problem since Kant.
- For the specific science of a specific regional object, logic must be constrained by an object structure.
- It is “*modal*” in Kant's sense w.r.t. a “*Phoronomy*” .

- To day, I think that one of the best framework for transcendental logic is topos theory, which
  - expresses the “object structure” by some category  $\mathcal{C}$ ,
  - formulates the theory by a certain type of functors  $\mathcal{C} \rightarrow \underline{\mathbf{Ens}}$ .



- Topos
  - pull backs,
  - terminal object,
  - exponentials i.e. internal Hom,
  - subobject classifier.
- Seaves, sites, sheaves.

- Saunders Mac Lane - Ieke Moerdijk (first sentence of *Sheaves in Geometry and Logic*, 1992) :

“A startling aspect of topos theory is that it unifies two seemingly wholly distinct mathematical subjects : on the one hand topology and algebraic geometry and on the other hand, logic and set theory.”

- The topos Ens is purely logic, without object structure.
- As claimed Ferdinand Gonseth,  
“la logique est la physique de l'objet  
quelconque.”

# Bohr topos and K-S

- Interpretation of K-S in the late 90s by Chris Isham, Jeremy Butterfield, Andreas Döring, Chris Heunen, Bas Spitters, etc.
- The approach is mainly “foundational, structural and conceptual”.
- How to ascribe truth values to judgments ?
- They use the “interplay between spatial and logical structures inherent to topos theory.” (Heunen)

# Bohr topos

## Born rule

Example of *elementary* propositions (“yes” or “no” questions)

$$a \in \Delta$$

with  $a \in \mathcal{B}_{s.a.}(\mathcal{H})$  and  $\Delta \subset \mathbb{R}$  (Borel subset).

If  $\psi \in \mathcal{H}$ ,  $a \in \mathcal{B}_{s.a.}(\mathcal{H})$ , and  $[a \in \Delta]$  projector,

*Born rule:* the probability for  $a \in \Delta$  to be true in state  $\psi$  is

$$\langle \psi, a \in \Delta \rangle = \|[a \in \Delta] \psi\|^2$$

A definite truth value  $V(a \in \Delta)$  (not a probability) exists iff

$$\begin{cases} [a \in \Delta] \psi = \psi \text{ then } V = 1 \\ [a \in \Delta] \psi = 0 \text{ then } V = 0 \end{cases}$$

If we want more general truth values, since hidden variables don't work, we need a non classical truth object (subobject classifier)  $\Omega$ .

$\Omega$  must *reflect* the object structure.

Logic must be “internalized” and become a transcendental logic.

## Classical case

$M$  = phase space,

category (poset, frame i.e. distributive complete lattice)

$\mathcal{O}(M)$  of open subsets.

states = points  $x \in M$ ,

observable = real function  $a : M \rightarrow \mathbb{R}$ ,

$$a \in \Delta \text{ true} \Leftrightarrow a(x) \in \Delta \Leftrightarrow x \in a^{-1}(\Delta).$$



A point  $x$  defines a valuation  $V_x$  on propositions  $a \in \Delta$  with values in  $\Omega = \{0, 1\}$ :

$$\begin{cases} V_x(a \in \Delta) = 1 & \text{if } a(x) \in \Delta \\ V_x(a \in \Delta) = 0 & \text{if } a(x) \notin \Delta \end{cases}$$

# Gelfand-Neimark-Segal

( $M$  compactified)

The algebra  $\mathfrak{A}_{s.a.}$  of observables  $\subset$   
the commutative  $C^*$ -algebra

$$\mathfrak{A} = C(M, \mathbb{C}), a : M \rightarrow \mathbb{R}.$$

A *state* is a map  $\rho : \mathfrak{A} \rightarrow \mathbb{C}$  which is  $\mathbb{C}$ -linear, positive, normalized.

$\rho(a)$  is the value of the observable  $a$  in the state  $\rho$ .

Let  $\Sigma = \text{Spec}(\mathfrak{A})$ ,  $\Sigma \simeq M$ .

*Gelfand duality*:  $\mathfrak{A} = C(\Sigma, \mathbb{C})$ , i.e.

$$a \Leftrightarrow \hat{a} : \Sigma \rightarrow \mathbb{C} \Leftrightarrow \tilde{a} : C(\mathbb{R})_0 \rightarrow \mathfrak{A}$$

where  $C(\mathbb{R})_0$  is the unitalization of the algebra of functions with compact support on  $\mathbb{R}$  (compactification of  $\mathbb{R}$ ).

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The map  $\tilde{a} : C(\mathbb{R})_0 \rightarrow \mathfrak{A}$  corresponds to the *functional calculus* FUNC on  $\mathfrak{A}$ , that is

$$\tilde{a}(1) = a, \text{ and } \tilde{a}(f(x)) = f(a).$$

The state  $\rho$  defines a probability measure  $\mu_\rho$  on  $\Sigma$  (Riesz theorem) and  $\rho(a) = \int_\Sigma \widehat{a}(x) d\mu_\rho(x)$ .

If the state  $\rho$  is not only  $\mathbb{C}$ -linear but also a morphism of *algebras*, then it is a point  $x$  of  $\Sigma$ ,  $\rho = \delta_x$ .

Points  $x \in \Sigma \iff$  valuations  $V_x : \mathfrak{A} \rightarrow \mathbb{C}$  defined by  $V_x(a) = \widehat{a}(x)$ .

## Gleason theorem

If  $\mathfrak{A}$  is no longer commutative, the states would a priori be only *quasi*-states  $\rho : \mathfrak{A} \rightarrow \mathbb{C}$  which are  $\mathbb{C}$ -linear only on the commutative sub- $C^*$ -algebra  $C$  of  $\mathfrak{A}$ .

But Gleason theorem (1957):

If  $\mathcal{H}$  is a separable Hilbert space of  $\dim \geq 3$  and if  $\mathfrak{A} = \mathcal{B}(\mathcal{H})$  then every quasi-state is a state.

- In QM we need  $\Omega \neq \{0, 1\}$ .
- Quantum logic is not satisfactory.
- Isham's & Co strategy is to “localize” truth to *partial* and *contextual* valuations defines only on the commutative sub- $C^*$ -algebras  $C$ .
  - Philosophical relations with modal theory (Bas Van Fraassen, Richard Healey, Jeffrey Bub, etc.).
  - Mathematical relations with topos theory.



Let  $\mathfrak{A}$  be the  $C^*$ -algebra describing the system.

Let  $\mathcal{C}(\mathfrak{A})$  be the small category (poset) of *commutative* sub- $C^*$ -algebra of  $\mathfrak{A}$ .

Let  $\mathcal{T}(\mathfrak{A}) = Sh(\mathcal{C}(\mathfrak{A}))$  be the topos of sheaves over  $\mathcal{C}(\mathfrak{A})$ .

The natural topology of  $\mathcal{C}(\mathfrak{A})$  is defined by the upper-sets  $U$  over  $C$

(i.e.  $U \subseteq C^\uparrow$  the maximal upper-set over  $C$  and if  $D \in U$  and  $D \subset E$  then  $E \in U$ ).

If  $\overline{F} \in \mathcal{T}(\mathfrak{A})$ , it is equivalent to the *covariant* functor  $F : \mathcal{C}(\mathfrak{A}) \rightarrow \mathbf{Ens}$  defined by  $F(C) = \overline{F}(C^\uparrow)$ .

Indeed,  $C \subset D \Rightarrow D^\uparrow \subset C^\uparrow$  since

$$D \subset E \Rightarrow C \subset D \subset E \text{ i.e. } C \subset E$$

The terminal object  $1$  of  $\mathcal{T}(\mathfrak{A})$  is the constant functor.

Pullbacks are computed pointwise.

For the exponentials

$$F^G(C) = \text{Nat}(G_{C^\uparrow}, F_{C^\uparrow})$$

$$F^G(\mathbb{C}.1) = \text{Nat}(G, F)$$

As the maximal upper-sets  $C^\uparrow$  are sub-categories of  $\mathcal{C}(\mathfrak{A})$ , if  $F \in \mathcal{T}(\mathfrak{A})$ , we can consider the restrictions of  $F$  to the  $C^\uparrow$ . We note that  $\mathbb{C}.1^\uparrow = \mathcal{C}(\mathfrak{A})$ .

The subobject classifier is defined by

$$\begin{aligned}\Omega(C) &\rightarrow \mathcal{U}_C = \{\text{upper sets } U \text{ over } C\} \\ \Omega(C \subset D) &= \mathcal{U}_C \rightarrow \mathcal{U}_D, U \in \mathcal{U}_C \mapsto U \cap D^\uparrow \in \mathcal{U}_D\end{aligned}$$

$$\begin{aligned}\Omega^F(C) &\simeq \text{Sub}(F_{C^\uparrow}) \\ \Omega^F(\mathbb{C}.1) &\simeq \text{Sub}(F) \\ \Omega^F(C \subset D) &= \text{restriction of the } \text{Sub}(F_{C^\uparrow}) \text{ to the } \text{Sub}(F_{D^\uparrow})\end{aligned}$$

The key point is that *inside* the topos  $\mathcal{T}(\mathfrak{A})$ , the *identity* functor  $\underline{\mathfrak{A}}: \mathcal{C}(\mathfrak{A}) \rightarrow \mathbf{Ens}$ ,  $C \mapsto C$ , defines an *internal commutative  $C^*$ -algebra*.

$(\mathcal{T}(\mathfrak{A}), \underline{\mathfrak{A}})$  is called the *Bohr topos*.

As  $\underline{\mathfrak{A}}$  is *commutative* we can apply Gelfand theory but *inside*  $\mathcal{T}(\mathfrak{A})$ .

We get an *internal* Gelfand spectrum  $\underline{\Sigma}$  which synthesizes the Gelfand spectra  $\Sigma_C$ .

This NC “phase space”  $\underline{\Sigma}$  can be described *externally* by a frame  $\mathcal{O}(\underline{\Sigma})$  (distributive complete lattice) of “open sets”, but this frame doesn’t come from any classical topological space.

## The interpretation of K-S in the Bohr topos

K-S means that the *internal* Gelfand spectrum  $\underline{\Sigma}$  has *no* points (it is point free).

Indeed, a point is a morphism

$$\rho : 1 \rightarrow \underline{\Sigma}$$

(that is a morphism  $\rho^{-1} : \mathcal{O}(\underline{\Sigma}) \rightarrow \Omega$ ).

Internally, observables  $a$  are elements of

$$\underline{\mathcal{A}}_{s.a.} : C \rightarrow C_{s.a.}$$

If  $a \in \underline{\mathcal{A}}_{s.a.}$ , its Gelfand transform is  $\hat{a} : \underline{\Sigma} \rightarrow \underline{\mathbb{R}}$  where  $\underline{\mathbb{R}}$  is the constant sheaf  $\mathbb{R}$ .

$\hat{a} \circ \rho : 1 \rightarrow \underline{\Sigma} \rightarrow \underline{\mathbb{R}}$  is a point of  $\underline{\mathbb{R}}$ .



We get a map

$$\underline{V}_\rho : \underline{\mathfrak{A}}_{s.a.} \rightarrow \text{Pt}(\underline{\mathbb{R}})$$

$$\underline{V}_\rho(C) = \underline{\mathfrak{A}}_{s.a.}(C) = C_{s.a.} \rightarrow \text{Pt}(\underline{\mathbb{R}})(C) = \mathbb{R}$$

One shows that  $\underline{V}_\rho(C) = C_{s.a.} \rightarrow \mathbb{R}$  is a morphism of algebras and is therefore a *valuation*.

K-S implies it is impossible. Therefore a point  $\rho$  of  $\underline{\Sigma}$  can't exist.

We can also say that  $\underline{\Sigma}$  is a “fibration”  $\underline{\pi}$  over  $\mathcal{C}(\mathcal{A})$  with fibers  $\Sigma_C \rightarrow C$ . A point  $\rho : 1 \rightarrow \underline{\Sigma}$  is in fact a *global section* of  $\underline{\pi}$  and K-S means that  $\underline{\pi}$  has no global sections.